

Basics of Matlab

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MATLAB Course

- 1. Getting started; Matlab Help;**
- 2. Variables;**
- 3. Operators;**
- 4. Matlab functions;**
- 5. Matrices;**
- 6. Scripts;**
- 7. Basic plotting.**
- 8. User Defined Functions**
- 9. Importing Data**
- 10. Simulink**
- 11. Flow Control Commands**

Where to find Matlab?

1. Matlab is installed on all computers in the public labs (i.e. HL230, library, etc)

2. To install Matlab on your personal computer go to:

<http://www.wpi.edu/academics/CCC/Help/Software/Installs/matlab.html>

or google for WPI Matlab

3. Run Matlab on the terminal server windows.wpi.edu with Remote Desktop or using Virtual Lab Web Access

<http://www.wpi.edu/academics/CCC/Help/Software/termserv.html>

Additional Matlab Resources and Training

Matlab Lecture Notes at blackboard.wpi.edu →
SESA Training

To access SESA Training web site:

1. Log in to the blackboard.wpi.edu
2. Once you have logged into Blackboard, click on the **Community** tab at the top of the page
3. In the '**Organization Search**' text box type **SESA** and click "**Go**".
4. The organization information will be displayed in the Search Results. Click the down arrows located to the right of the Organization ID and then click on **Enroll**
5. An "Action Successful" enrollment message will appear on the screen. Click the **OK** button to access the organization.

- Registration at:

<http://www.wpi.edu/Regi/CCC/sesa.html>

- Customized Matlab training sessions, if more than 5-7 students are interested in.

The screenshot shows the 'myWPI Campus Community' website. At the top, there is a navigation bar with 'Home', 'Help', and 'Logout' links. Below this is a vertical menu of red buttons for various software tools: MATLAB, MATHCAD, ANSYS, FLUENT, LABVIEW, Registration & Schedules, Staff Information, Training Reports, and Announcements. To the right of this menu is a 'Tools' section with links for Communication, Organization Tools, Organization Map, Control Panel, Refresh, and Detail View. The main content area on the right features several training session announcements, each with a folder icon and a title: 'Customized sessions for WPI Courses (Fall07-Spring)', 'Crash Course in MATLAB' (with sub-topics: Introduction to Matlab, Using Matlab, Matlab Visualization & Specialized Tools), 'Matlab Refresher Course' (described as an intensive training session), 'Data Analysis with Matlab' (with sub-topics: Preparing Data for Analysis, Data Fitting), 'Basics of Matlab' (described as a six-hour hands-on session), and 'MATLAB Programming for Continuum Mechanics'.

Matlab Resources

MATWORKS web site

+Tutorials on Specific Topics and Features

Each video shows a specific feature or application example. Topics range from basic to advanced.

<http://www.mathworks.com/products/matlab/examples.html> (MATLAB Overview, Getting Started, Mathematics, Graphics and Visualization, Programming)

+Interactive MATLAB & Simulink Based Tutorials

An interactive video-based tutorial that introduces MATLAB capabilities and programming **Getting Started** (Tutorials for Beginners)

http://www.mathworks.com/academia/student_version/start.html

+MATLAB recorded webinars

<http://www.mathworks.com/company/events/webinars/index.html>

Introduction to MATLAB (for beginners)

+Short Simulink examples

<http://www.mathworks.com/products/simulink/examples.html>

+MATLAB Central

You can learn more about how MathWorks products are used by visiting [MATLAB Central](#).

<http://www.mathworks.com/matlabcentral/>

Experiments with MATLAB, by Cleve Moler

Online textbook that introduces MATLAB through the use of interesting puzzles and problems

http://www.mathworks.com/moler/exm/chapters.html?s_cid=edu_cr_1532

What is Matlab ?

- **MATLAB®** is a high-performance language for **technical computing**.
- It integrates **computation**, **visualization**, and **programming** in an *easy-to-use environment* where problems and solutions are expressed in familiar mathematical notation.
- **MATLAB** stands for **matrix laboratory**.
- MATLAB is an interactive system whose **basic data element** is an **matrix (array)** that **does not require dimensioning**.
- This allows you to solve many technical computing problems, especially those with matrix and vector formulations, in a fraction of the time it would take to write a program in a scalar non-interactive language such as C or Fortran.

MATLAB System

1. The MATLAB Language

(matrix language with loops, functions, data structures..)

2. Development Environment (desktop, windows, browsers,..)

3. The MATLAB Mathematical Function Library; Toolboxes

4. Graphics (data visualization, image processing, animation)

5. The MATLAB External Interfaces (API)

(a library that allows you to write C and Fortran programs that interact with MATLAB)

Starting Matlab

- *Windows:* Start menu → Matlab → Matlab
- *Unix:* Terminal window → type **matlab**

Matlab Window

Menu

Current Directory

The screenshot shows the MATLAB environment with several windows and callouts:

- Menu:** Points to the top menu bar containing File, Edit, Debug, Desktop, Window, and Help.
- Current Directory:** Points to the address bar showing the current directory as C:\matlabR14sp2\work.
- Workspace Window:** A window showing a table of variables in the workspace:

Name	Value
a	5
b	7
c	12
- Command Window:** A window showing the execution of MATLAB commands and their output:

```
To get started, select MATLAB Help or Demos from the Help menu.  
>> a=5;  
>> b=7;  
>> c=a+b  
  
c =  
  
    12  
  
>>
```
- History Window:** A window showing the command history:

```
%-- 2/20/06 1:19 PM --%  
%-- 2/20/06 1:21 PM --%  
  a=5;  
  b=7;  
  c=a+b
```

Matlab Help

1. Using **HELP** menu → **MATLAB Help**

HELP → **Using Help Browser**

2. `>> helpdesk` **Opens the Help browser.**

3. `>> help commandname/toolboxname/functionname`

Ex: `>> help sin`

4. `>> doc commandname/toolboxname/functionname`

displays the detailed info in the Help browser.

Ex: `>> doc sin`

Other commands:

5. `>> lookfor = helpdesk -> search`

I. Matlab Programming

➤ **Matlab Variables**

➤ **Numbers**

➤ **Operators**

➤ **Functions**

.....

Matlab Variables

- A MATLAB variable is essentially **a tag that you assign to a value in memory.**
- MATLAB does not require any type declarations or dimension statements.
- When MATLAB encounters a new variable name, it automatically creates the variable and allocates the appropriate amount of storage.
- If the variable already exists, MATLAB changes its contents.
- **Variable names** consist of **a letter**, followed by any number of **letters, digits, or underscores.**
- MATLAB uses only **the first 31 characters** of a variable name.
- MATLAB is **case sensitive**; it distinguishes between uppercase and lowercase letters.
- MATLAB stores variables in a part of memory called **workspace.**
- To view what is stored in a variable type its name.

Types of Variables: MATLAB provides three basic types of variables:

Local Variables

Global Variables

Persistent Variables

Matlab Variables

Rules for variable names:

- Make Sure Variable Names Are Valid
- Don't Use Function Names for Variables
- Check for Reserved Keywords
- Avoid Using *i* and *j* for Variables

Syntax:

```
variableName=Value;
```

Example:

```
>> a=5;  
>> b=7;  
>> c=a+b  
>> method='linear'
```

How to remove a variable from workspace:

```
>> clear variableName
```

```
>> clear - removes all variables from the workspace (!!!!)
```

ans = default variable, when the result is not assign to a variable

Exercise: 1. Define $a1=8$ and $b2=8$, $c1=a1+b2$

2. Other commands: `variable= input('prompt')` (`>>help input`)

```
>> a3=input('a3=')
```

Numbers

1. Integers

Matlab has 8,16,32, 64 bit , signed and unsigned integer data types.

(`int8`, `int16`, `int32`, `int64`, `uint8`, `uint16`, `uint32`, `uint64`)

2. **floating-point numbers:** in either **double-precision (64 bits)**
or **single-precision (32 bits)** format.

(`double`, `single`)

3. **Imaginary numbers** use either `i` or `j` as a suffix

Ex: `5+2i` `6 -3.14159j`

4. Infinity and NaN

Useful related functions: `realmax` , `realmin` , `intmin` , `intmax` , `eps`
`isnan`, `format`

Numbers

eps – function that returns the distance from 1.0 to the next largest double-precision number

d = eps(X) is the positive distance from `abs(X)` to the next larger in magnitude floating point number of the same precision as X.

inf Infinity : **division by zero** and **overflow**, which lead to results too large to represent as conventional floating-point values.

ex: `1/0`, `1.e1000`

NaN Not-a-Number: a result of mathematically undefined operations like `0.0/0.0` and `inf-inf`.

Related commands: `edit`

Numbers

1. - decimal notation (with an optional decimal point and leading plus or minus sign)

Ex: 3 -99 0.0001

2. . Scientific notation (uses the letter **e** to specify a **power-of-ten scale factor**.)

Ex: 1.60210e-5 6.02252e10

All numbers are stored internally using the long format specified by the IEEE floating-point standard. Floating-point numbers have a finite precision of roughly 16 significant decimal digits and a finite range of roughly 10^{-308} to 10^{+308} .

Useful related functions: **realmax** , **realmin** , **intmin** , **intmax** , **eps**
isnan , **format**

Strings

```
>> name = 'John'    % create a string variable  
>> errorMessage= 'negative number'
```

Useful related functions: `num2str`, `str2num`, `strcat`

Operators

Expressions use familiar **arithmetic operators** and precedence rules.

<code>+</code>	Addition
<code>-</code>	Subtraction
<code>*</code>	Multiplication
<code>^</code>	Power
<code>'</code>	Complex conjugate transpose
<code>()</code>	Specify evaluation order

Functions

1. Standard elementary mathematical functions

```
>> help elfun
```

Trigonometric (`sin`, `cos`)

Exponential (`exp`, `log`)

Complex (`abs`, `angle`)

Rounding and remainder (`round`)

2. Elementary matrices and matrix manipulation.

```
>> help elmat
```

3. Specialized math functions.

```
>> help specfun
```

<code>pi</code>	3.14159265...
<code>i</code>	Imaginary unit, $\sqrt{-1}$
<code>j</code>	Same as <code>i</code>
<code>eps</code>	Floating-point relative precision, $\epsilon = 2^{-52}$
<code>Inf</code>	Infinity
<code>NaN</code>	Not-a-number

Functions

1. Built-in functions (Ex. `sqrt`, `sin`)

Some of the functions, like `sqrt` and `sin`, are built in.

Built-in functions are part of the MATLAB core

They are very efficient

The computational details are not readily accessible.

(you cannot see the code)

2. Function implemented in M-files (ex. `factorial`, `mean`, `det`)

You can see the code and even modify it, if you want.

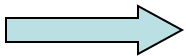
Syntax:

```
>> outputArgs = functionName(inputArgs)
```

✓ I. Matlab Programming

We talked about:

- ✓ **Matlab Variables**
- ✓ **Numbers**
- ✓ **Operators**
- ✓ **Functions**



III. Matlab Programming

....

- **Matrices**
- **Operators**
- **Functions**

.....

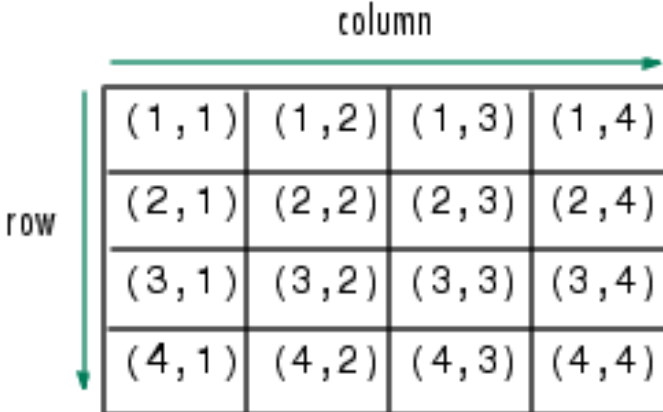
Matrix & basic matrix functions

Define a matrix:

1. Type the matrix
2. Use Specialized Matrix Functions

Matrix Manipulation

Matrix Functions



A 4x4 matrix is shown with a grid of cells. Each cell contains a pair of coordinates (row, column). A green arrow labeled 'row' points downwards on the left side of the grid. A green arrow labeled 'column' points to the right above the grid.

(1, 1)	(1, 2)	(1, 3)	(1, 4)
(2, 1)	(2, 2)	(2, 3)	(2, 4)
(3, 1)	(3, 2)	(3, 3)	(3, 4)
(4, 1)	(4, 2)	(4, 3)	(4, 4)

Matrix: Define a matrix

1. Type the matrix

- Separate the elements of a row with **blanks** or **commas**.
- Use a **semicolon**, ; , to indicate the end of each row.
- Surround the entire list of elements with **square brackets**, [].

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 21 & 22 & 23 \\ 31 & 32 & 33 \end{bmatrix}$$

```
1. >> A=[1 2 3; 21 22 23; 31 32 33];
```

```
2. >> A=[1, 2, 3; 21, 22, 23; 31, 32, 33];
```

```
3. >> A(1,1)=1; A(1,2)=12; A(1,3)=13; A(2,1)=21; A(2,2)=22;  
A(2,3)=23;
```

Basic matrix information: **size** (size of a matrix)
>> [m,n] = size(X)

Matrix: Define a matrix

2. Use Specialized Matrix Functions

Function	Description
ones	Create a matrix or array of all ones.
zeros	Create a matrix or array of all zeros.
eye	Create a matrix with ones on the diagonal and zeros elsewhere.
diag	Create a diagonal matrix from a vector.
rand	Create a matrix or array of uniformly distributed random numbers.
randn	Create a matrix or array of normally distributed random numbers and arrays.

```
>> B=eye(3)
```

B =

```
1 0 0
0 1 0
0 0 1
```

```
>> C=ones(2,3)
```

C =

```
1 1 1
1 1 1
```

D =

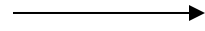
```
0.4289
0.3046
0.1897
0.1934
```

```
>> D=rand(4,1)
```

Matrix: Accessing Matrix Elements

■ individual element

```
>> A(2,2)
```

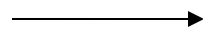


```
ans =  
    22
```

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 21 & 22 & 23 \\ 31 & 32 & 33 \end{bmatrix}$$

■ column

```
>> A(:,2)
```

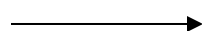


```
ans =  
     2  
    22  
    32
```

■ (colon) → all elements

■ row

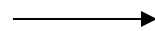
```
>> A(2,:)
```



```
ans =  
    21    22    23
```

■ group of elements

```
>> A(2,1:2)
```



```
ans =  
    21    22
```

first element : step: last element

Matrix: Operations

<code>+</code>	Addition
<code>-</code>	Subtraction
<code>*</code>	Multiplication
<code>/</code>	Division
<code>\</code>	Left division (described in "Mat
<code>^</code>	Power
<code>'</code>	Complex conjugate transpose
<code>()</code>	Specify evaluation order

`A+B`

`A-B`

`A*B`

`A/B`

`A\B`

`A^B`

`A'`

<code>.*</code>	Element-by-element multiplication
<code>./</code>	Element-by-element division
<code>.\</code>	Element-by-element left division
<code>.^</code>	Element-by-element power
<code>.'</code>	Unconjugated array transpose

`A.*B`

`A./B`

`A.\B`

`A.^B`

`A.'`

Matrix: Operations

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \\ 2 & 2 & 2 \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} 10 & 20 & 30 \\ 11 & 21 & 31 \\ 1 & 2 & 3 \end{bmatrix},$$

```
>> A=[1 2 3; 2 3 1; 2 2 2];
```

```
>> B= [10 20 30; 11 21 31; 1 2 3];
```

```
>> A*B
```



ans =			
	35	68	101
	54	105	156
	44	86	128

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{bmatrix},$$

$$\mathbf{A} \cdot * \mathbf{B} = \begin{bmatrix} a_{11} \cdot b_{11} & a_{12} \cdot b_{12} & a_{13} \cdot b_{13} \\ a_{21} \cdot b_{21} & a_{22} \cdot b_{22} & a_{23} \cdot b_{23} \\ a_{31} \cdot b_{31} & a_{32} \cdot b_{32} & a_{33} \cdot b_{33} \end{bmatrix}$$

```
>> A.*B
```



ans =			
	10	40	90
	22	63	31
	2	4	6

Element by element multiplication

Matrix: Functions

Few matrix functions :

det -Determinant

trace -Sum of diagonal elements

linsolve-Solve linear systems of equations (using LU factorization)

eig - Find eigenvalues and eigenvectors

eigs -Find largest eigenvalues and eigenvectors of a sparse matrix

sdv - Singular value decomposition

balance -Improve accuracy of computed eigenvalues

**** - Linear equation solution

(**X = A\B** is the solution to the equation **AX = B**
computed by Gaussian elimination)

cond - condition number (the ratio of the
largest singular value to the smallest)

Matrix: Solution of a linear system

$\mathbf{X} = \mathbf{A} \backslash \mathbf{B}$ is the solution to the equation $\mathbf{AX} = \mathbf{B}$

computed by Gaussian elimination

A=square matrix

$$\begin{array}{rcl} x_1 + x_2 + x_3 = 2 & x_1 = ? \\ x_1 + 2x_2 + 3x_3 = 5 & x_2 = ? \\ x_1 + 3x_2 + 6x_3 = 7 & x_3 = ? \end{array}$$

$\backslash = \text{ldivide}$

```
>>A=[1,1,1;1,2,3;1,3,6];
```

```
>>b=[2;5;7];
```

```
1. >>x=A\b
```

```
2. >> x=linsolve(A,b)
```

```
3. >> x =inv(A)*b
```

$\mathbf{X} =$
-2
5
-1

($\mathbf{X} = \mathbf{A} \backslash \mathbf{B}$ is the solution to the equation $\mathbf{Ax} = \mathbf{b}$ computed by Gaussian elimination)

linsolve-Solve linear systems of equations (using LU factorization)

✓ III. Matlab Programming

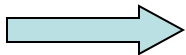
We talked about:

.....

- ✓ **Matrices**
- ✓ **Operators**
- ✓ **Functions**

.....

III. How to write a program (M-files)



IV. How to plot data

M-files

- **Files that contain code in the MATLAB** language are called *M-files*.
- You create M-files using a text editor.
- Use a M-file as any other MATLAB function or command.
- A M-file is a plain text file.

Two kinds of **M-files**:

Scripts

do not accept input arguments or *return output arguments*
operate on data in the workspace.

Functions

can accept input arguments and *return output arguments*
internal variables are local to the function.

M-files: Scripts

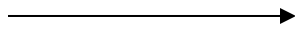
- do not accept input arguments or *return output arguments*
- operate on data in the workspace.

>> **edit** myScript

type the code

Example

File/Save



>> **myScript**

(to run the script type its name)

```
%myScript

% this is my script file
% calculates the determinant of A
clear
N=10;
theta=pi/N;
r=sin(theta);
```

% - indicates a comment

Matlab - Plotting

plot

Syntax:

`plot(y) ;` `plot(x,y) ;` `plot(x,y,s)`

The plot function has different forms, depending on the input arguments.

If **y** is a vector, `plot(y)` produces a piecewise linear graph of *the elements of y* versus the *index of the elements of y*.

If you specify two vectors as arguments, `plot(x,y)` produces a *graph of y versus x*.

Matlab - Plotting

```
plot(x,y, s);
```

s allows to plot : colors, symbols, different lines

b	blue	.	point	-	solid
g	green	o	circle	:	dotted
r	red	x	x-mark	-.	dashdot
c	cyan	+	plus	--	dashed
m	magenta	*	star	(none)	no line
y	yellow	s	square		
k	black	d	diamond		
				

```
plot(x,y,'c+:')
```

plots a cyan dotted line with a plus at each data point;

Matlab - Plotting

```
clear
t=0:0.01:10; % time seconds
signalSin=sin(2*pi*t); % signal1 - frequency =1 Hz
signalCos=0.5*cos(2*pi*t); % signal2 - frequency =1 Hz

figure
plot(t,signalSin);

hold on
plot(t,signalCos, '-*r');

xlabel('time'); ylabel('signal');
legend('Sin', 'Cos');
title('Two Signals', 'FontSize',12)
```

plot2signals.m

Other commands:

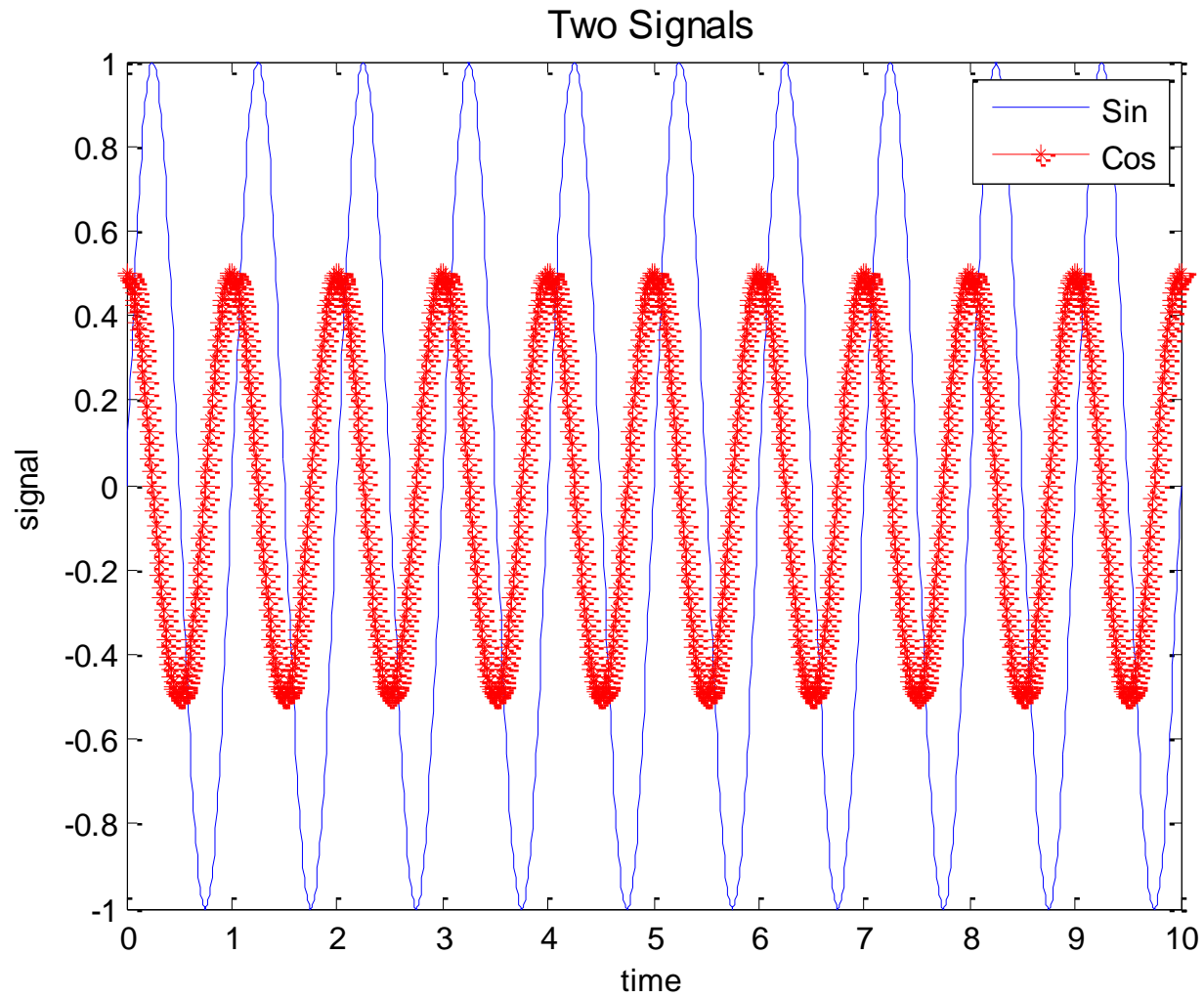
figure

xlabel

ylabel

legend, title

Matlab - Plotting



Matlab - Plotting

line

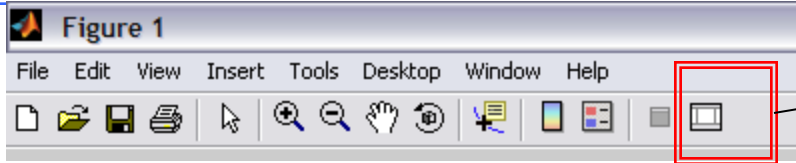
Create line object

Syntax

```
line(X,Y)
line(X,Y,Z)
line(X,Y,Z,'PropertyName',propertyvalue,...)
line('XData',x,'YData',y,'ZData',z,...)
h = line(...)
```

```
>> P1=[1,2];
>> P2=[3,4];
>> P3=[3,6];
>> line([P1(1), P2(1), P3(1)], [P1(2), P2(2), P3(2)])
```

Visualization - Interactive editing



show plot tools

Figure Palette

Axes subplots

Lineseries selected

Figure

Plot Browser

Property Editor - Lineseries

Display Name: Plot Type: Line

X Data Source: xlong Line: 0.5

Y Data Source: y1 Marker: none 6.0

Z Data Source:

Add Data...

Inspector...

Refresh Data...

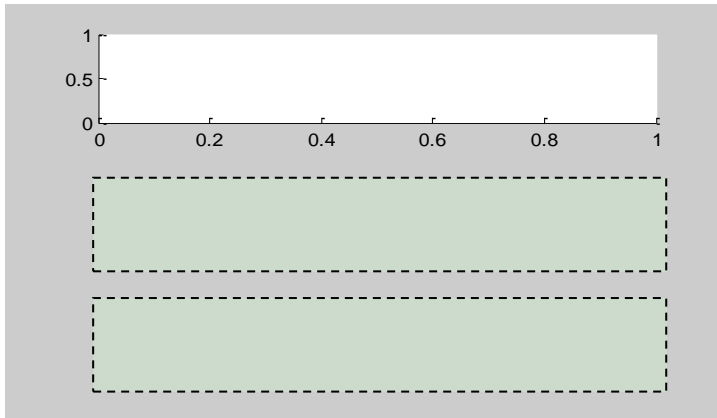
Property Editor displaying lineseries properties

Click to add data to axes

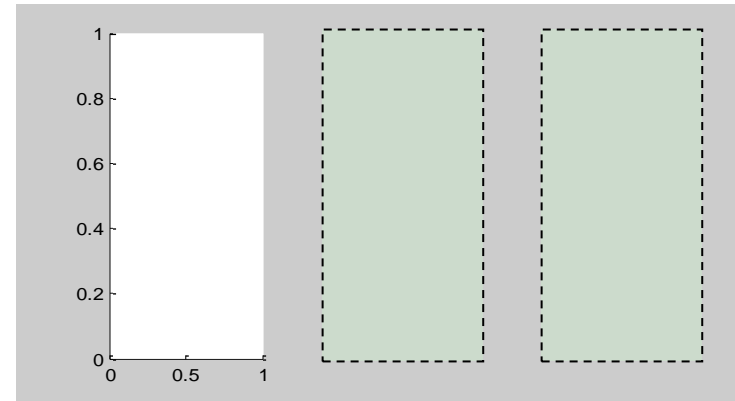
Click to display Property Inspector

Visualization - subplot

```
>> subplot(3,1,1)
```



```
>> subplot(1,3,1)
```



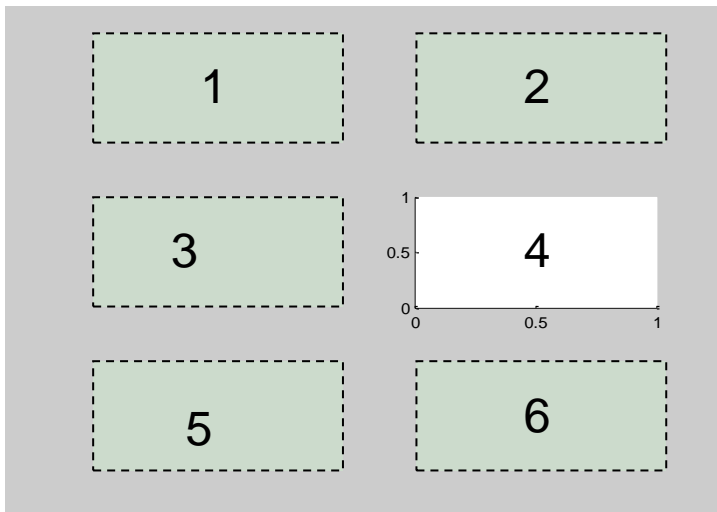
subplot(m,n,q)

* breaks the figure into a $m \times n$ matrix of windows.

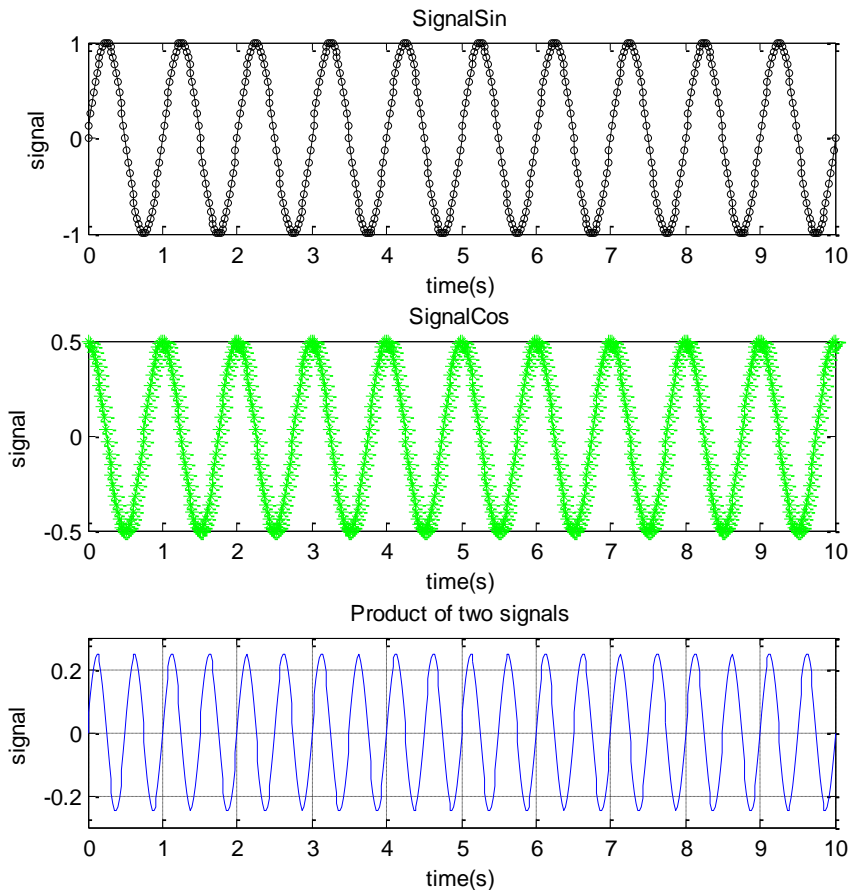
q = the current window

plot3Windows.m

```
>> subplot(3,2,4)
```



Visualization - subplot



`plot3Windows.m`

```
clear; % clear the workspace
close; % close previous figures

% Generate the signals
t=0:0.02:10; % time seconds
signalSin=sin(2*pi*t); % signal1 - frequency =1 Hz
signalCos=0.5*cos(2*pi*t); % signal2 - frequency =1 Hz
signal3=signalSin.*signalCos;

% Plot the signals
figure; subplot(3,1,1)
plot(t,signalSin,'-ok', 'MarkerSize',2);
title('SignalSin')
xlabel('time(s)'); ylabel('signal');

subplot(3,1,2)
plot(t,signalCos, '-*g');
title('SignalCos')
xlabel('time(s)'); ylabel('signal');

subplot(3,1,3)
plot(t,signal3);
grid
title('Product of two signals')
xlabel('time(s)'); ylabel('signal');
axis([0 10 -0.3 0.3]); % syntax: axis([XMIN XMAX YMIN YMAX])
```

Introduction to MATLAB

SUMMARY

1. Getting started; Matlab Help;
2. Variables;
3. Operators;
4. Matlab functions;
5. Matrices;
6. Scripts;
7. Basic plotting.
8. User Defined Functions
9. Importing Data
10. Simulink

FUNCTIONS

✓ Matlab functions & Toolboxes

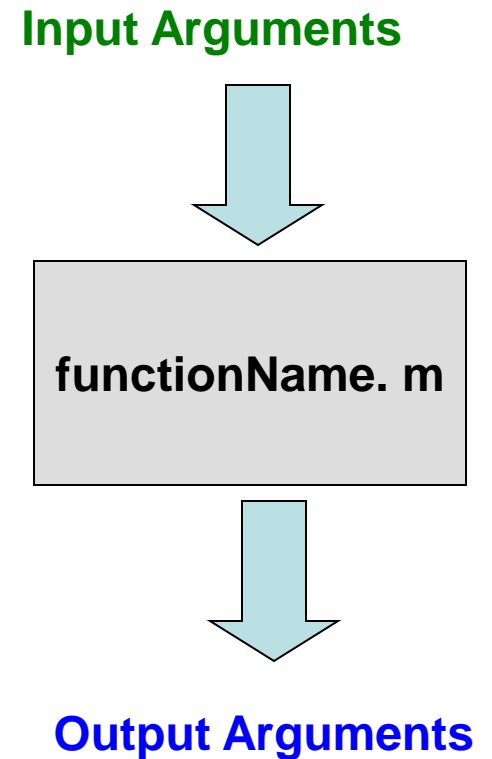
■ User Defined Functions

There are essentially two ways to create a new function in MATLAB:

1. in a file saved to permanent storage. (`.m file`)
2. in a command entered at run-time (`inline`, `anonymous`)

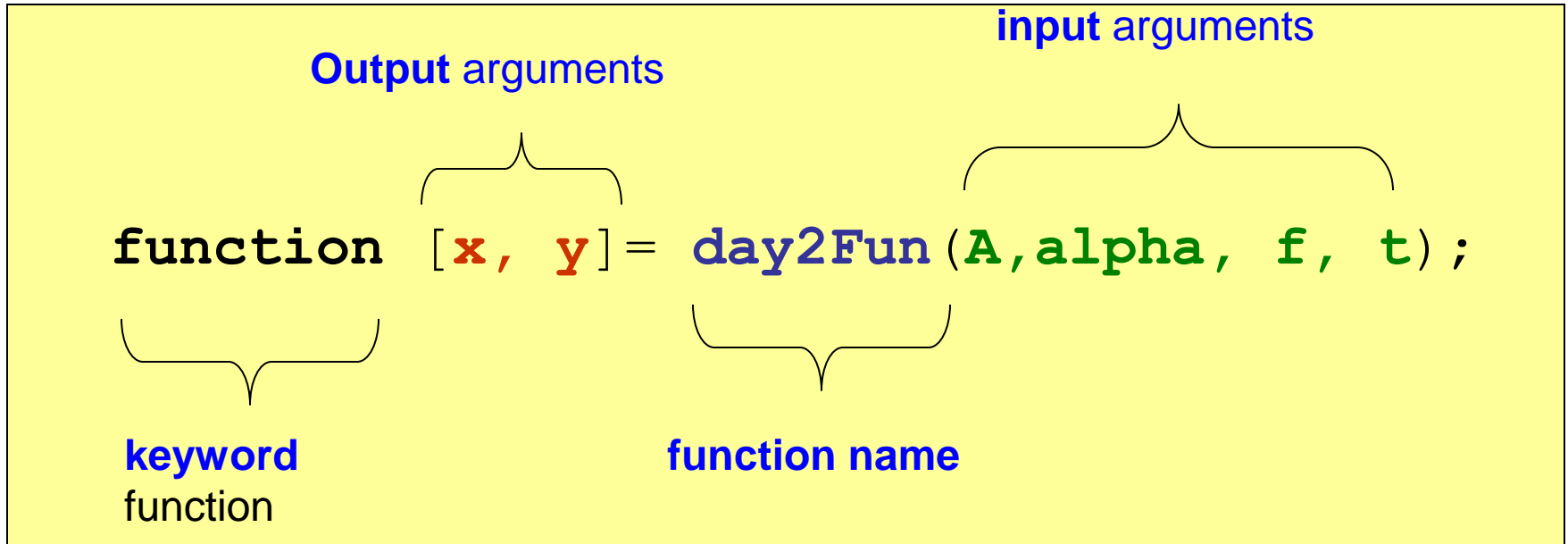
FUNCTIONS

- **Functions** are M-files that can accept **input arguments** and **return output arguments**.
- The M-file and function should have the same name.
- Each M-file function has an **area of memory**, called the **function workspace**, separate from the MATLAB base workspace, in which it operates.



FUNCTIONS

Function definition:



Calling the function:

```
>> [x1, y1] = day2Fun (A1, alpha1, f1, t1);
```

FUNCTIONS

Function definition:

day2Fun.m

```
function [x, y]=day2Fun(A,alpha, f, t);
```

exampleFun.m

```
%% function [x, y]=day2Function(A,alfa, f, t);
```

```
%% Lecture2: user defined functions in Matlab
```

```
amplitude=A*exp(-alpha*t);
```

```
x=amplitude.*sin(2*pi*f*t);
```

```
y=amplitude.*cos(2*pi*f*t);
```

Main code

```
>> clear all
```

```
>> A1=5;
```

```
>> alpha1=0.5;
```

```
>> f1=1;
```

```
>> t1=0:0.01:10;
```

```
>> [x1, y1]=day2Fun(A1,alpha1, f1, t1);
```

```
>> figure
```

```
>> plot(t1,x1, t1,y1);
```

```
>> legend('x1', 'y1')
```

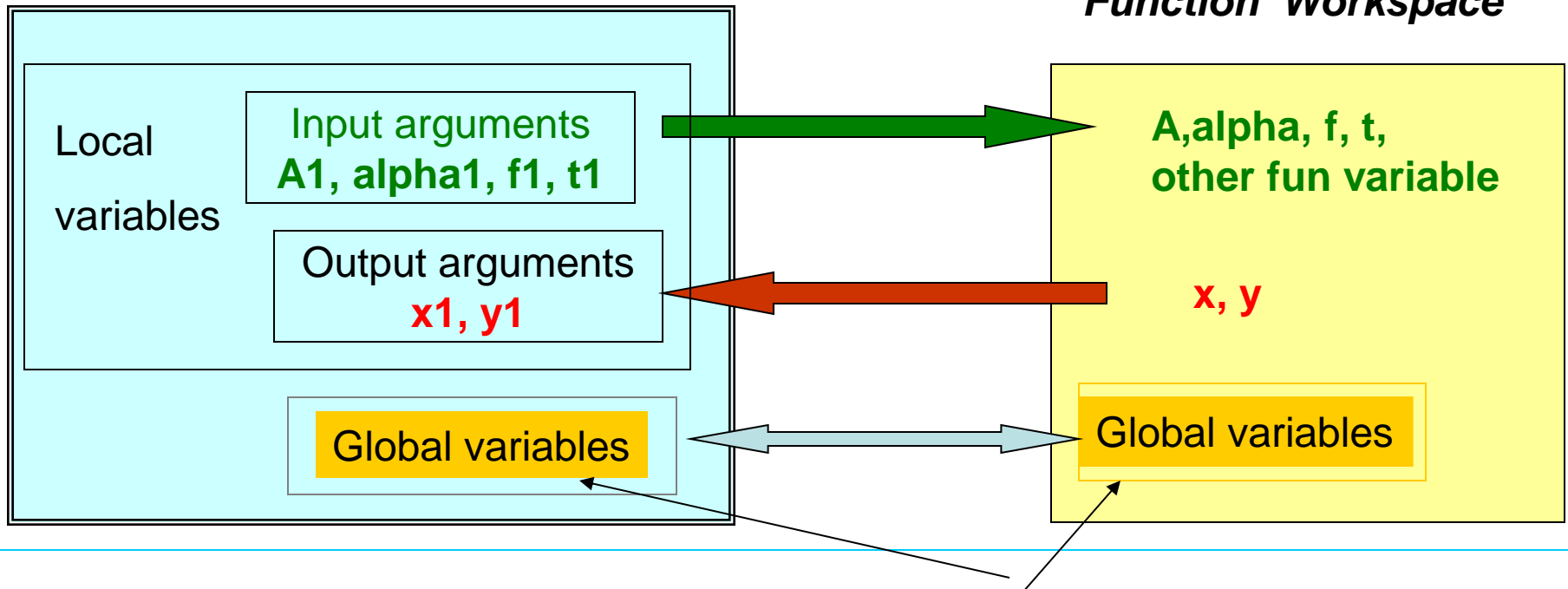
Function: Input and output arguments

```
function [x, y]= day2Fun(A,alpha, f, t);
```

```
>> [x1, y1]= day2Fun (A1,alpha1, f1, t1);
```

Matlab Workspace

Function Workspace



Global variables:

day2Fun2.m

exampleFun2.m

Shared workspace

FUNCTIONS: How to document a function

*the function-declaration
line*

keyword **function**
function name `trace`
order of arguments.

```
function t = trace(a)
```

```
%TRACE Sum of diagonal elements.
```

```
% TRACE(A) is the sum of the diagonal elements of A,  
which is
```

```
% also the sum of the eigenvalues of A.
```

```
%
```

```
% Class support for input A:
```

```
% float: double, single
```

```
% Copyright 1984-2004 The MathWorks, Inc.
```

```
% $Revision: 5.8.4.1 $ $Date: 2004/04/10 23:30:11 $
```

```
t = sum(diag(a));
```

executable code

*The
help
text*

```
>> trace(A)
```

```
>> results= trace(A);
```


Function: Inline functions

There are essentially two ways to create a new function in MATLAB:

1. in a command entered at run-time (`inline` and `anonymous`)
2. or in a file saved to permanent storage.

```
inline function, feval  
  
>> f=inline('x^2+y^2', 'x', 'y')  
  
f =  
  
    Inline function:  
    f(x,y) = x^2+y^2  
  
>> m=f(1,2)  
  
m =5
```

1.1 Importing and Exporting Data

1.1.2 Supported File Formats

File Format	File Content	Extension	Functions
MATLAB formatted	Saved MATLAB workspace	.mat	load , save
Text	Text	any	textscan
	Text	any	textread
	Delimited text	any	dlmread , dlmwrite
	Comma-separated numbers	.csv	csvread , csvwrite
Extended Markup Language	XML-formatted text	.xml	xmlread , xmlwrite
Audio	NeXT/SUN sound	.au	auread , auread
	Microsoft WAVE sound	.wav	wavread , wavwrite
Movie	Audio/video	.avi	aviread
Scientific data	Data in Common Data Format	.cdf	cdfread , cdfwrite
	Flexible Image Transport System data	.fits	fitsread
	Data in Hierarchical Data Format	.hdf	hdfread
Spreadsheet	Excel worksheet	.xls	xlsread , xlswrite
	Lotus 123 worksheet	.wk1	wk1read , wk1write
Graphics	TIFF image	.tiff	imread , imwrite
	PNG image	.png	same
	HDF image	.hdf	same
	BMP image	.bmp	same
	JPEG image	.jpeg	same

1. Importing and Exporting Data

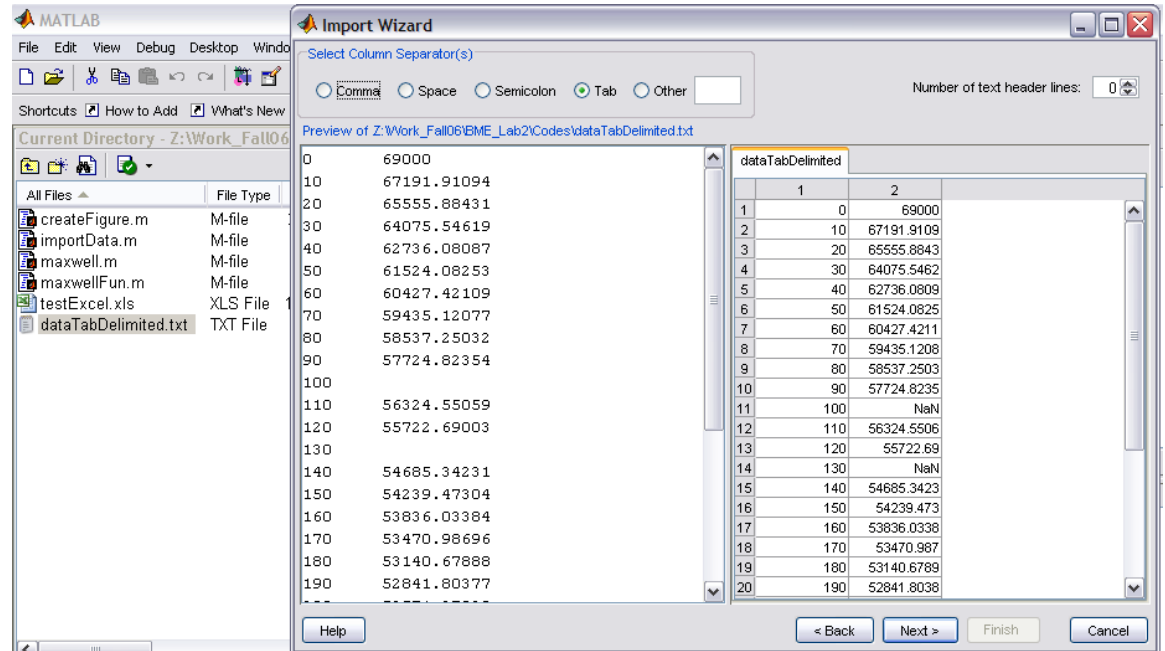
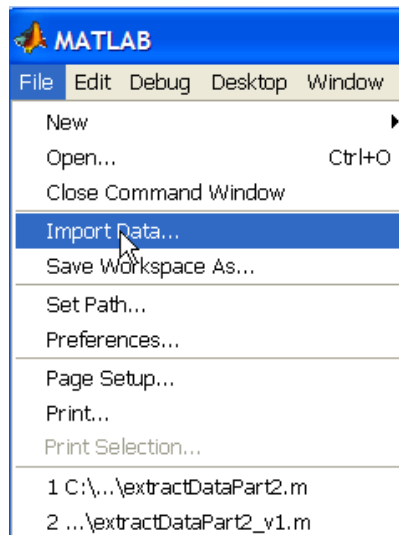
- **using the Import Wizard**
- **save , load**
- **dlmread , dlmwrite**
- **xlsread, xlswrite**
- **fopen, , fscanf, fprintf**

1.1 Importing and Exporting Data

1.1.1 Using the Import Wizard with Text Data

File → Import Data

or **>> uiimport**



1.1.2 Supported File Formats

Wizard: missing data: NaN (Not-a-Number.)

1.1 Importing & exporting data: dlmread & dlmwrite

dlmread, **dlmwrite** - Read/Write ASCII delimited file.

prepareData.m

Syntax

```
M = dlmread(filename)
M = dlmread(filename, delimiter)
M = dlmread(filename, delimiter, R, C)
M = dlmread(filename, delimiter, range)
```

add at the end of
existing file

```
data=dlmread('myFile');
dlmwrite(fileName, data, 'delimiter', '\t', '-append');
dlmwrite(fileName, data, '\t')
```

fileName matrix to be saved

Delimiter = tab

```
data=dlmread('dataCSV.csv', ',', 2, 0);
```

dlmread reads from the ASCII-delimited numeric data file filename to output matrix M. The delimiter separating data elements is inferred from the formatting of the file.

Comma (,) is the default delimiter.

1.1 Importing & exporting data: dlmread & dlmwrite

`dlmread`, `dlmwrite` - Read/Write ASCII delimited file.

Syntax

```
M = dlmread(filename)
M = dlmread(filename, delimiter)
M = dlmread(filename, delimiter, R, C)
M = dlmread(filename, delimiter, range)
```

```
for i=1:4
    fileName=['results', num2str(i), '.csv']
    data(i, :, :) = dlmread(fileName, ',', 2, 0);
end
```

1.1 Importing & exporting data: `xlswrite`, `xlsread`

`xlswrite`, `xlsread` - Write/Read Excel file.

```
xlswrite('filename', data)
```

```
xlsread('filename')
```

To import Excel data by wizard (`uiimport`) the file should have the extension **.xls**

SIMULINK

SIMULINK

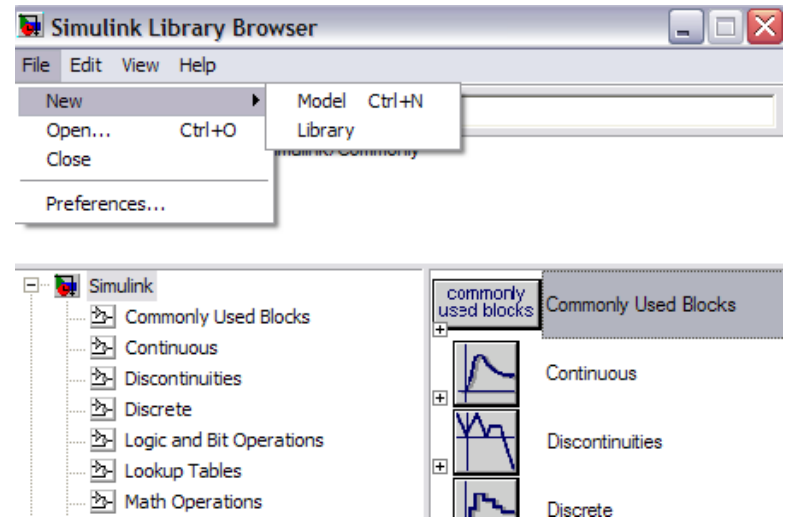
Simulink® is software for modeling, simulating, and analyzing dynamic systems.

It supports linear and nonlinear systems, modeled in continuous time, sampled time, or a hybrid of the two.

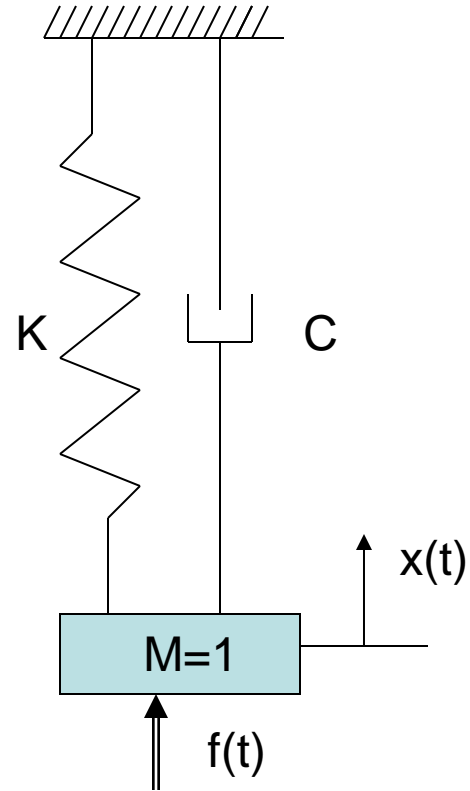
Systems can also be multirate, i.e., have different parts that are sampled or updated at different rates.

For modeling, Simulink provides a graphical user interface (GUI) for building models as block diagrams, using click-and-drag mouse operations.

>> `simulink`



Response of a SDOF (nDOFs) system



Linear systems: time and laplace domains

Time Domain

$$\ddot{x} + C_d \dot{x} + Kx = f(t)$$

$$x_1 = x$$

$$x_2 = \dot{x} = \dot{x}_1$$

$$x(t_0), \dot{x}(t_0)$$

$$\dot{x}_1 = x_2$$

$$\dot{x}_2 = -C_d x_2 - Kx_1 + f(t)$$

$$y = x$$

Laplace Domain

F(s)

$$H(s) = \frac{1}{(s^2 + C_d s + K)}$$

X(s)

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -K & -C_d \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} f(t)$$

$$y = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \end{bmatrix} f(t)$$

$$\dot{\mathbf{x}} = \mathbf{Ax} + \mathbf{B}f$$

parameters.m

$$\mathbf{y} = \mathbf{Cx} + \mathbf{D}f$$

Linear systems: time and laplace domains

Time
Domain

$$\ddot{x} + C_d \dot{x} + Kx = f(t)$$

$$x(t_0), \dot{x}(t_0)$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -K & -C_d \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} f(t)$$
$$y = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \end{bmatrix} f(t)$$

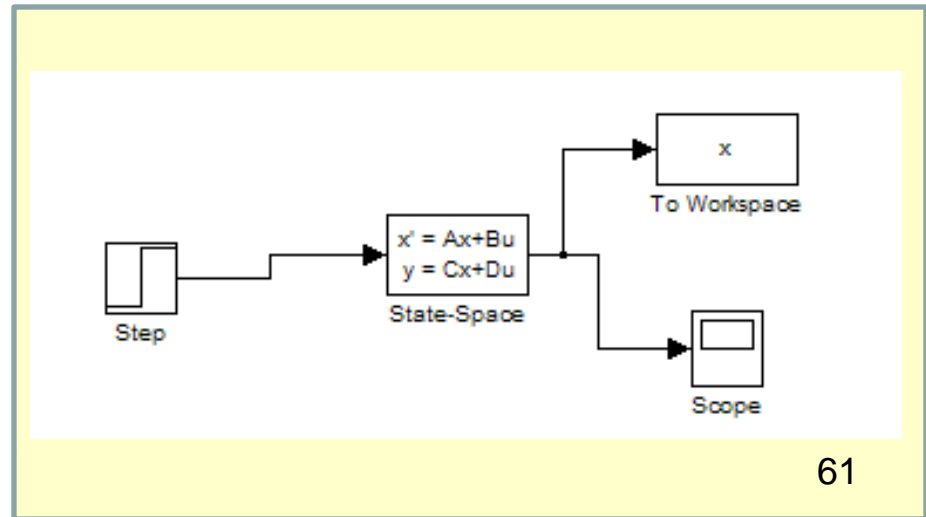
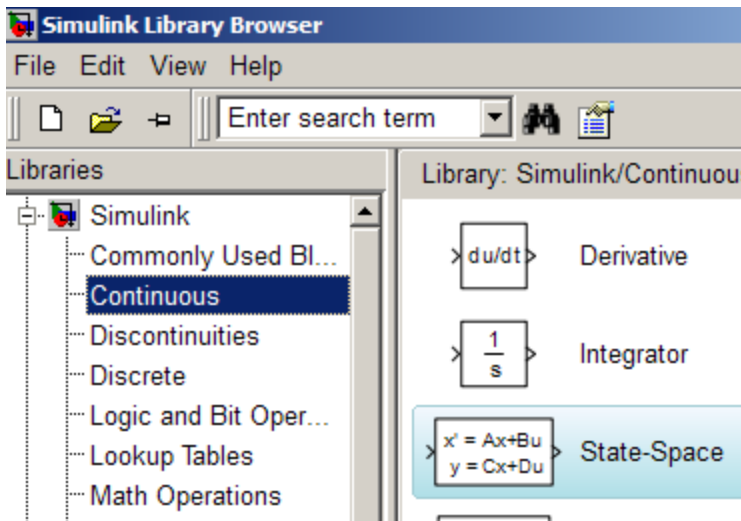
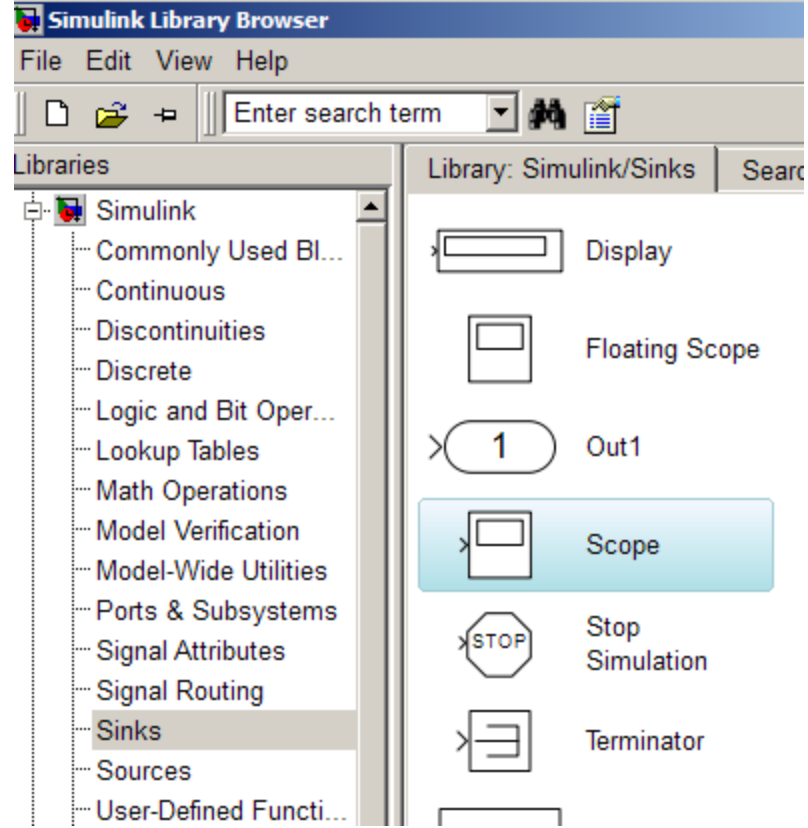
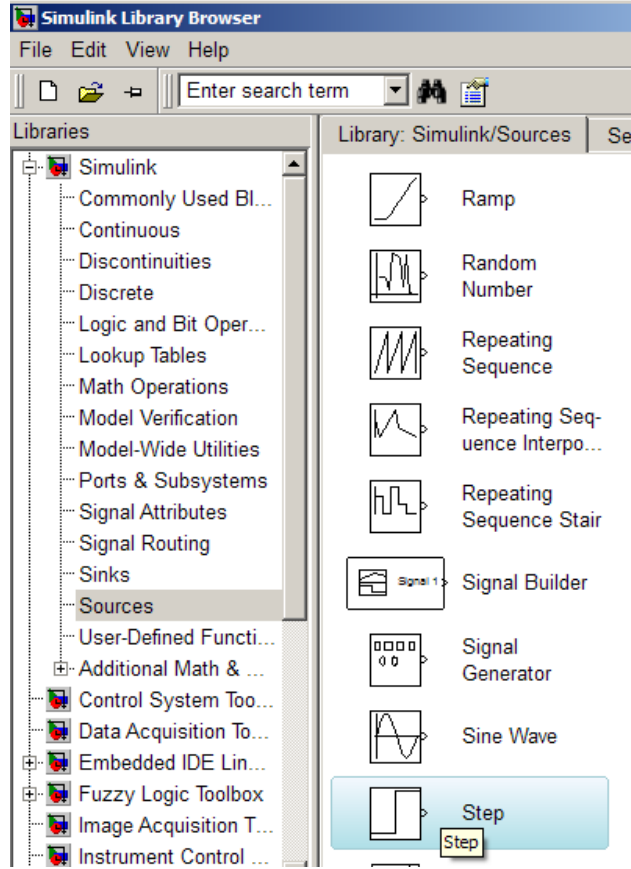
$$\dot{\mathbf{x}} = \mathbf{A}\mathbf{x} + \mathbf{B}f$$

$$\mathbf{y} = \mathbf{C}\mathbf{x} + \mathbf{D}f$$

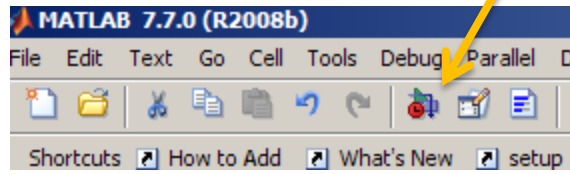
→ $y = x$

parameters.m

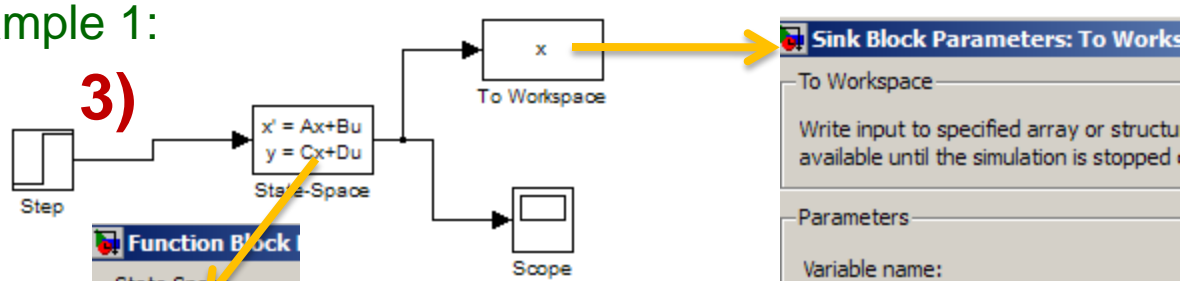
Example 1:



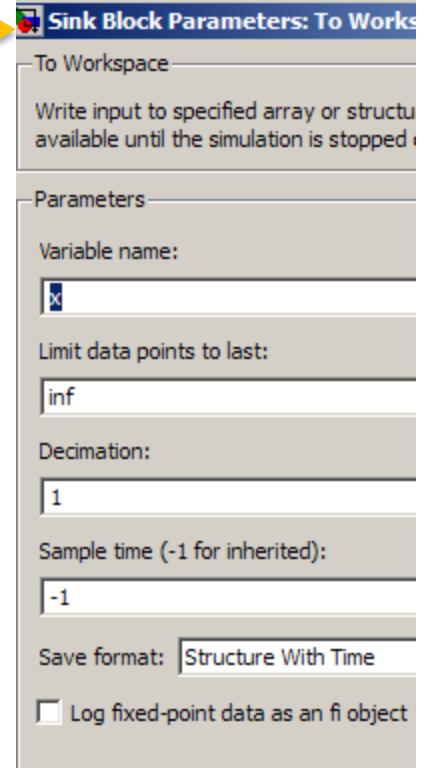
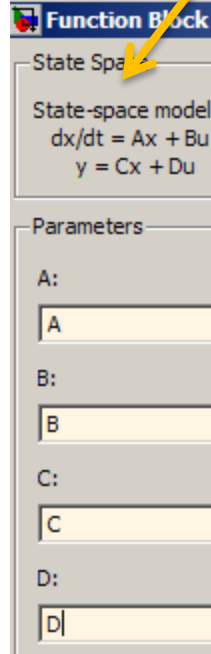
0) Start simulink



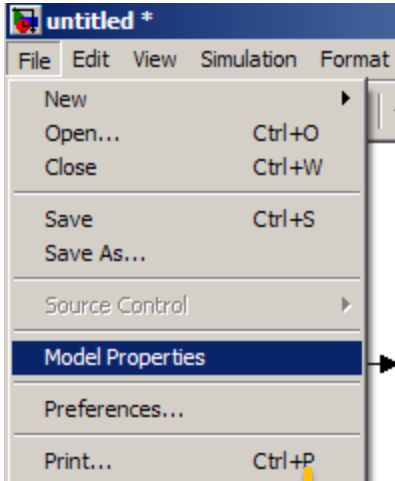
Example 1:



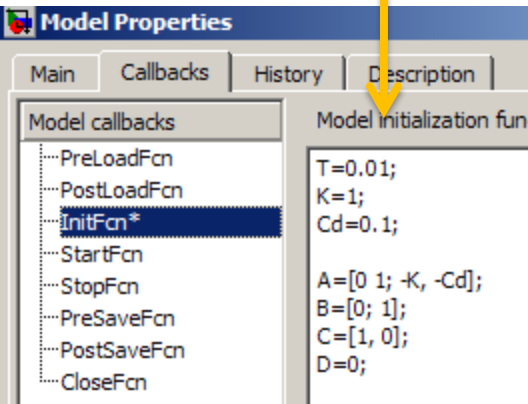
3)



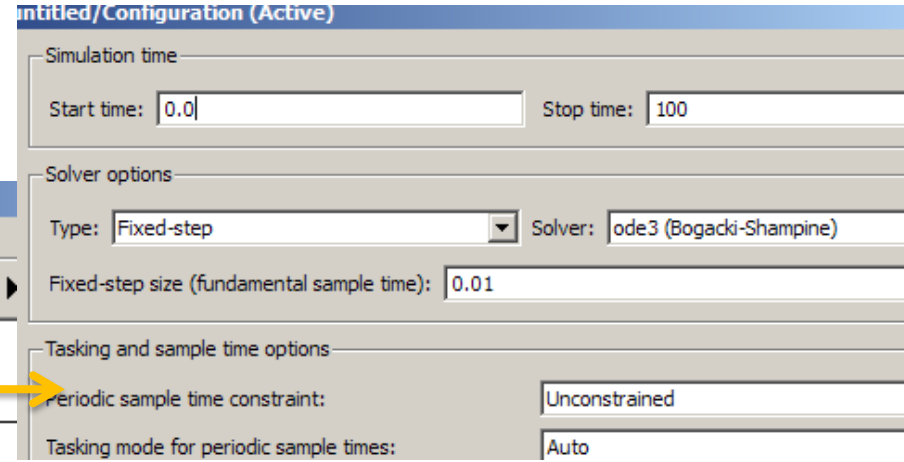
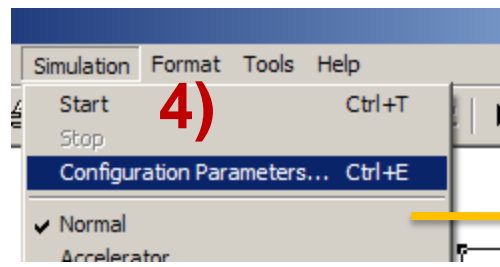
1)



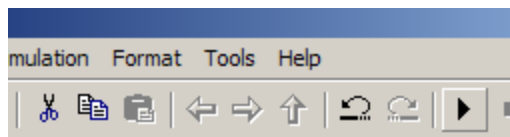
2)



4)



5) Run the model



```
clear all; close all;
```

```
% set the sample period in sec.
```

```
Ts = 0.01;
```

```
% Set the parameter values
```

```
K=1;
```

```
Cd=.1;
```

```
% Fill in the state space configuration
```

```
A = [0,1;-K,-Cd];
```

```
B = [0;1];
```

```
C = [1,0];
```

```
D = 0;
```

```
% Run the simulink simulation 'sim1'
```

```
sim sim1
```

```
% Plot the results
```

```
plot(t,x)
```

Configuration Parameters: sim1/Configuration (Active)

Select:

- Solver
- Data Import/Export
- Optimization
- Diagnosics
 - Sample Time
 - Data Validity
 - Type Conversion
 - Connectivity
 - Compatibility
 - Model Referencing
 - Saving
- Hardware Implementation
- Model Referencing

Simulation time

Start time: 0.0

Stop time: 100

Solver options

Type: Fixed-step

Solver: ode3 (Bogacki-Shampine)

Fixed-step size (fundamental sample time): .01

Tasking and sample time options

Periodic sample time constraint:

Unconstrained

Tasking mode for periodic sample times:

Auto

Another approach: Example 2:

Function Block Parameters: State-Sp

State Space

State-space model:

$$dx/dt = Ax + Bu$$

$$y = Cx + Du$$

Parameters

A:

A

B:

B

C:

C

D:

D

Initial conditions:

0

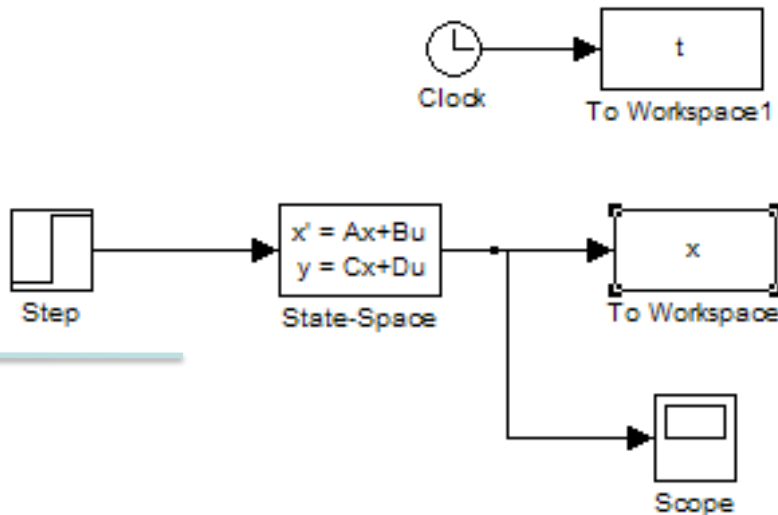
Absolute tolerance:

auto

State Name: (e.g., 'position')

"

OK



To Workspace

Write input to specified array or structure in MATLAB's main workspace. Data is not available until the simulation is stopped or paused.

Parameters

Variable name:

x

Limit data points to last:

inf

Decimation:

1

Sample time (-1 for inherited):

-1

Save format: Array

Log fixed-point data as an fi object

OK

Cancel

Help

Apply

Loops (Flow Control)

MATLAB has several flow control commands:

`if`, `else`, and `elseif`

`switch` and `case`

`for`

`while`

`continue`

`break`

`return`

Flow Control: if ... else

if : conditionally executes statements

```
if relation
    statements 1
else
    statements 2
end
```

Example:

```
a=5; b=7;
if a>b
    disp('a greater than b');
else
    disp('b greater than a');
end
```

```
if expression1
    statements1
elseif expression2
    statements2
else
    statements3
end
```

Flow Control: for

The **for** loop executes a group of statements a number of times.

```
for variable = expression  
statements  
end
```

Example:

```
for n = 1:5  
    r(n) = n^2;  
end  
r
```

expression:

first value: last value

first value: step: last value

Change of increment:

```
for n = 1:2:10; statement; end;
```

```
for n=10:-1:1; statement; end;
```

Flow Control: while

The **while** loop executes a group of statements until a logical test is false.

```
while expression  
    statements  
end
```

Example:

```
a=1;  
while a>0.1  
    a=rand  
end
```

Other commands:

rand

Flow Control: switch, case

Ex: Find the structure of the command.

```
>> help switch  
>> doc switch
```

My Example:

```
clear  
a=6; b=2;  
method=input(' method=' );  
switch method  
    case 1  
        c=a+b;  
    case 2  
        c=a*b;  
    case 3  
        c=a/b;  
    otherwise  
        disp('no valid method')  
end
```

files: exSwitch.m

exSwitch2.m

Other commands: **input**, **disp**

Loops: Exit commands

break

Lets you exit early from a **for** loop or **while** loop.

In nested loops, **break** exits from the innermost loop only.

return

Terminates the current sequence of commands.

Returns control to the invoking function or to the keyboard.

Ctrl + C

Emergency exit

✓ III. Matlab - Programming

We talked about:

✓ **Relational operators** (>, <, <=, >=...)

✓ **Loops (Flow Control)**

✓ **if, else, and elseif**

✓ **switch** and **case**

✓ **for**

✓ **while**

✓ **continue**

✓ **break**

✓ **return**

